

All about “cosine” and truncated cosine in CT

Discrete Time Systems

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Fourier series of the cosine “with Euler”

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$$x(t) = \cos(\omega_0 t)$$



- For Euler...

$$\cos(\omega_0 t) = \frac{1}{2} [e^{j\omega_0 t} + e^{-j\omega_0 t}]$$



- Sum of complex exponentials...
this is already the Fourier Series !!!

Fourier series of the cosine “with Euler”

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- Sum of complex exponentials...
- this is already the Fourier Series !!!

$$a_1 = \frac{1}{2}, \quad a_{-1} = \frac{1}{2},$$

$$a_k = 0 \text{ for all } k \neq -1, 1$$

Fourier series of the cosine “with definition” of a_k

Fourier series of the cosine “with definition” of a_k

$$a_k = \frac{1}{T_0} \int_{T_0} x(t) e^{-jk\omega_0 t} dt$$

Note that ω_0 inside the cosine is exactly ω_0 , that is,
the fundamental frequency of the signal...

$$= \frac{1}{T_0} \int_{T_0} \cos(\omega_0 t) e^{-jk\omega_0 t} dt$$

$$= \frac{1}{2T_0} \int_{T_0} (e^{j\omega_0 t} + e^{-j\omega_0 t}) e^{-jk\omega_0 t} dt$$

$$= \frac{1}{2T_0} \int_0^{T_0} (e^{j\omega_0 t} + e^{-j\omega_0 t}) e^{-jk\omega_0 t} dt$$

Fourier series of the cosine “with definition” of a_k

$$\begin{aligned} a_k &= \frac{1}{2T_0} \int_0^{T_0} (e^{j\omega_0 t} + e^{-j\omega_0 t}) e^{-jk\omega_0 t} dt \\ &= \frac{1}{2T_0} \int_0^{T_0} (e^{j(1-k)\omega_0 t} + e^{-j(1+k)\omega_0 t}) dt \\ &= \frac{1}{2T_0} \int_0^{T_0} e^{j(1-k)\omega_0 t} dt + \frac{1}{2T_0} \int_0^{T_0} e^{-j(1+k)\omega_0 t} dt \end{aligned}$$



Now we focus on this integrals....

Fourier series of the cosine “with definition” of a_k

we can do more calculus (and also divide in cosine and sine, if you need/desire),
the pure complex exponential...

but if we recognize we are integrating *virtually* a cosine/sine signal in its period
then we can easily write:

(Recall that $\omega_0 = \frac{2\pi}{T_0}$)

$$\int_0^{T_0} e^{j(1-k)\omega_0 t} dt = 0 \quad \text{for } k \neq 1$$

$$\int_0^{T_0} e^{-j(1+k)\omega_0 t} dt = 0 \quad \text{for } k \neq -1$$

Fourier series of the cosine “with definition” of a_k

For $k=1$, and $k=-1$:

$$\int_0^{T_0} e^{j(1-1)\omega_0 t} dt = \int_0^{T_0} 1 \cdot dt = T_0$$

$$\int_0^{T_0} e^{-j(1-1)\omega_0 t} dt = \int_0^{T_0} 1 \cdot dt = T_0$$

Fourier series of the cosine “with definition” of a_k

Finally, we obtain:

$$a_k = \frac{1}{2T_0} \int_0^{T_0} e^{j(1-k)\omega_0 t} dt + \frac{1}{2T_0} \int_0^{T_0} e^{-j(1+k)\omega_0 t} dt$$

$$a_1 = \frac{1}{2T_0} T_0 + 0 = \frac{1}{2} + 0 = \frac{1}{2}$$

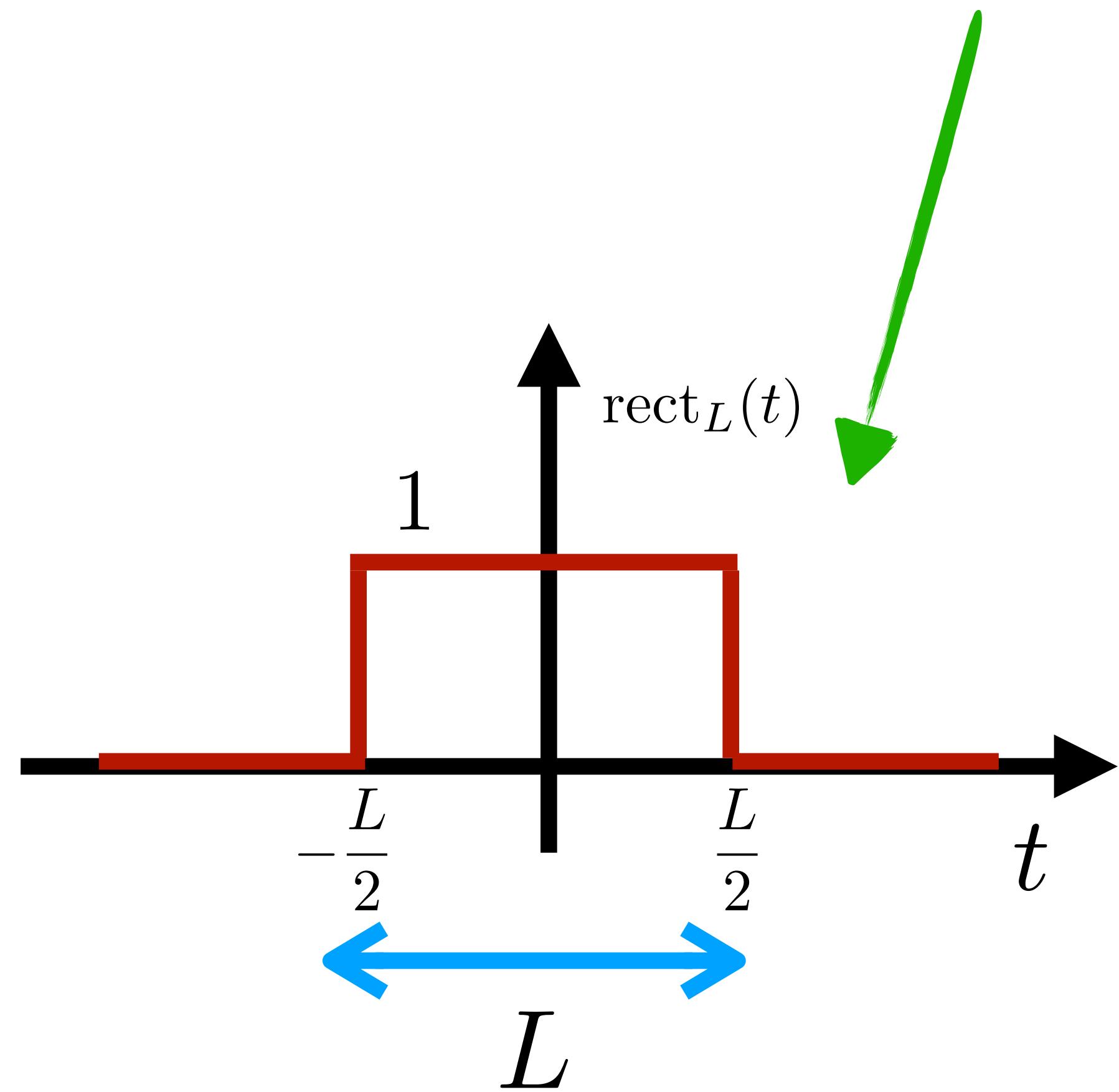
$$a_{-1} = 0 + \frac{1}{2T_0} T_0 = 0 + \frac{1}{2} = \frac{1}{2}$$

$$a_k = 0, \quad \text{for all } k \neq 1, -1$$

Truncated cosine signal (method 1: from the “definition” of Standard FT)

Truncated cosine signal

$$x(t) = \cos(\omega_0 t) \text{rect}_L(t)$$



Truncated cosine signal: method 1

$$\begin{aligned} X(\omega) &= \int_{-\frac{L}{2}}^{\frac{L}{2}} \cos(\omega_0 t) e^{-j\omega t} dt \\ &= \frac{1}{2} \int_{-\frac{L}{2}}^{\frac{L}{2}} (e^{j\omega_0 t} + e^{-j\omega_0 t}) e^{-j\omega t} dt \\ &= \frac{1}{2} \int_{-\frac{L}{2}}^{\frac{L}{2}} e^{j(\omega_0 - \omega)t} dt + \frac{1}{2} \int_{-\frac{L}{2}}^{\frac{L}{2}} e^{-j(\omega_0 + \omega)t} dt \end{aligned}$$

Truncated cosine signal: method 1

$$X(\omega) = \frac{1}{2} \left[\frac{-1}{j(\omega - \omega_0)} e^{j(\omega_0 - \omega)t} \right]_{-\frac{L}{2}}^{\frac{L}{2}} + \frac{1}{2} \left[\frac{-1}{j(\omega + \omega_0)} e^{-j(\omega_0 + \omega)t} \right]_{-\frac{L}{2}}^{\frac{L}{2}}$$

$$X(\omega) = \frac{1}{2} \left[\frac{-e^{j(\omega_0 - \omega)\frac{L}{2}}}{j(\omega - \omega_0)} + \frac{e^{-j(\omega_0 - \omega)\frac{L}{2}}}{j(\omega - \omega_0)} \right] + \frac{1}{2} \left[\frac{-e^{-j(\omega_0 + \omega)\frac{L}{2}}}{j(\omega + \omega_0)} + \frac{e^{j(\omega_0 + \omega)\frac{L}{2}}}{j(\omega + \omega_0)} \right]$$

$$X(\omega) = \frac{1}{2} \left[\frac{-e^{-j(\omega - \omega_0)\frac{L}{2}} + e^{j(\omega - \omega_0)\frac{L}{2}}}{j(\omega - \omega_0)} \right] + \frac{1}{2} \left[\frac{-e^{-j(\omega_0 + \omega)\frac{L}{2}} + e^{j(\omega_0 + \omega)\frac{L}{2}}}{j(\omega + \omega_0)} \right]$$

Truncated cosine signal: method 1

$$X(\omega) = \frac{1}{2} \left[\frac{-e^{-j(\omega-\omega_0)\frac{L}{2}} + e^{j(\omega-\omega_0)\frac{L}{2}}}{j(\omega - \omega_0)} \right] + \frac{1}{2} \left[\frac{-e^{-j(\omega_0+\omega)\frac{L}{2}} + e^{j(\omega_0+\omega)\frac{L}{2}}}{j(\omega + \omega_0)} \right]$$

(for any doubts, recall also that $\sin(a) = \sin(-a)$)

$$X(\omega) = \frac{1}{2} \left[\frac{2j \sin((\omega - \omega_0)\frac{L}{2})}{j(\omega - \omega_0)} \right] + \frac{1}{2} \left[\frac{2j \sin((\omega + \omega_0)\frac{L}{2})}{j(\omega + \omega_0)} \right]$$

$$X(\omega) = \frac{\sin((\omega - \omega_0)\frac{L}{2})}{\omega - \omega_0} + \frac{\sin((\omega + \omega_0)\frac{L}{2})}{\omega + \omega_0}$$

Truncated cosine signal: method 1

This is already the solution:

$$X(\omega) = \frac{\sin((\omega - \omega_0)\frac{L}{2})}{\omega - \omega_0} + \frac{\sin((\omega + \omega_0)\frac{L}{2})}{\omega + \omega_0}$$

That can be written as sum of two “octopus”/pulpos:
(i.e., two sinc functions)

$$X(\omega) = \frac{1}{2}\text{sinc}_{\frac{L}{2}}(\omega - \omega_0) + \frac{1}{2}\text{sinc}_{\frac{L}{2}}(\omega + \omega_0)$$

Truncated cosine signal: method 1

$$X(\omega) = \frac{1}{2}\text{sinc}_{\frac{L}{2}}(\omega - \omega_0) + \frac{1}{2}\text{sinc}_{\frac{L}{2}}(\omega + \omega_0)$$

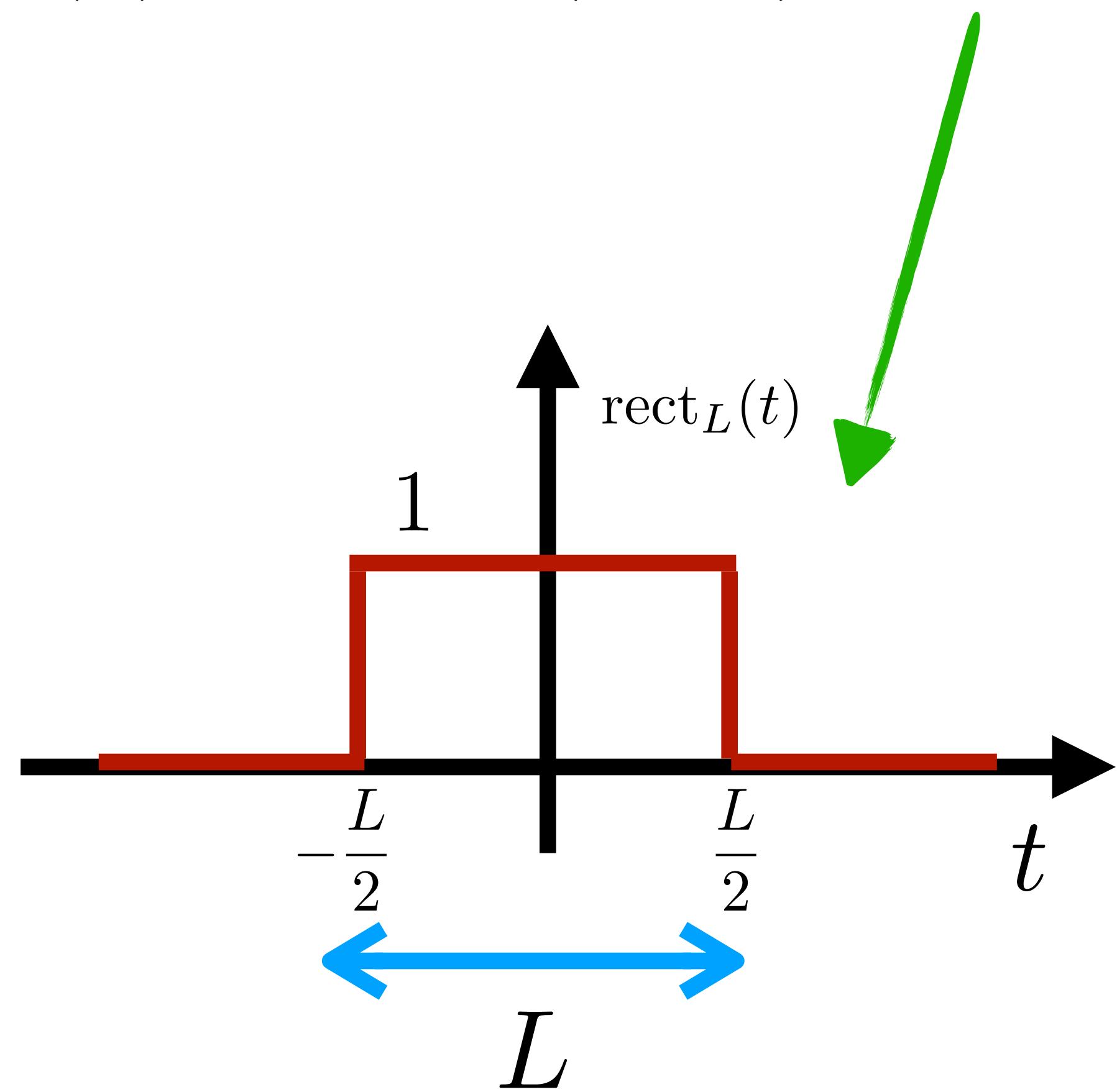
where:

$$\text{sinc}_{\frac{L}{2}}(\omega) = \frac{2 \sin(\omega \frac{L}{2})}{\omega}$$

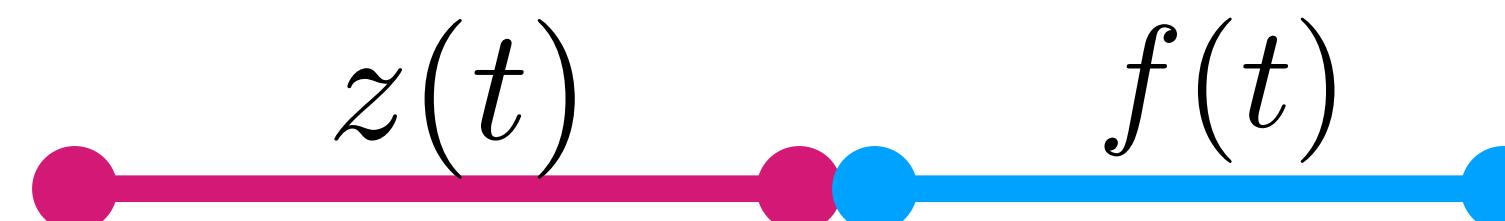
**Truncated cosine signal
(method 2: using properties...)**

Truncated cosine signal

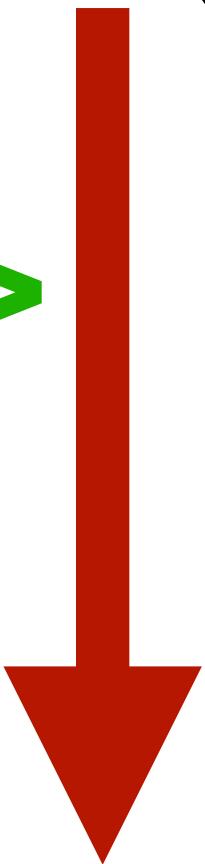
$$x(t) = \cos(\omega_0 t) \text{rect}_L(t)$$



Truncated cosine signal: method 2

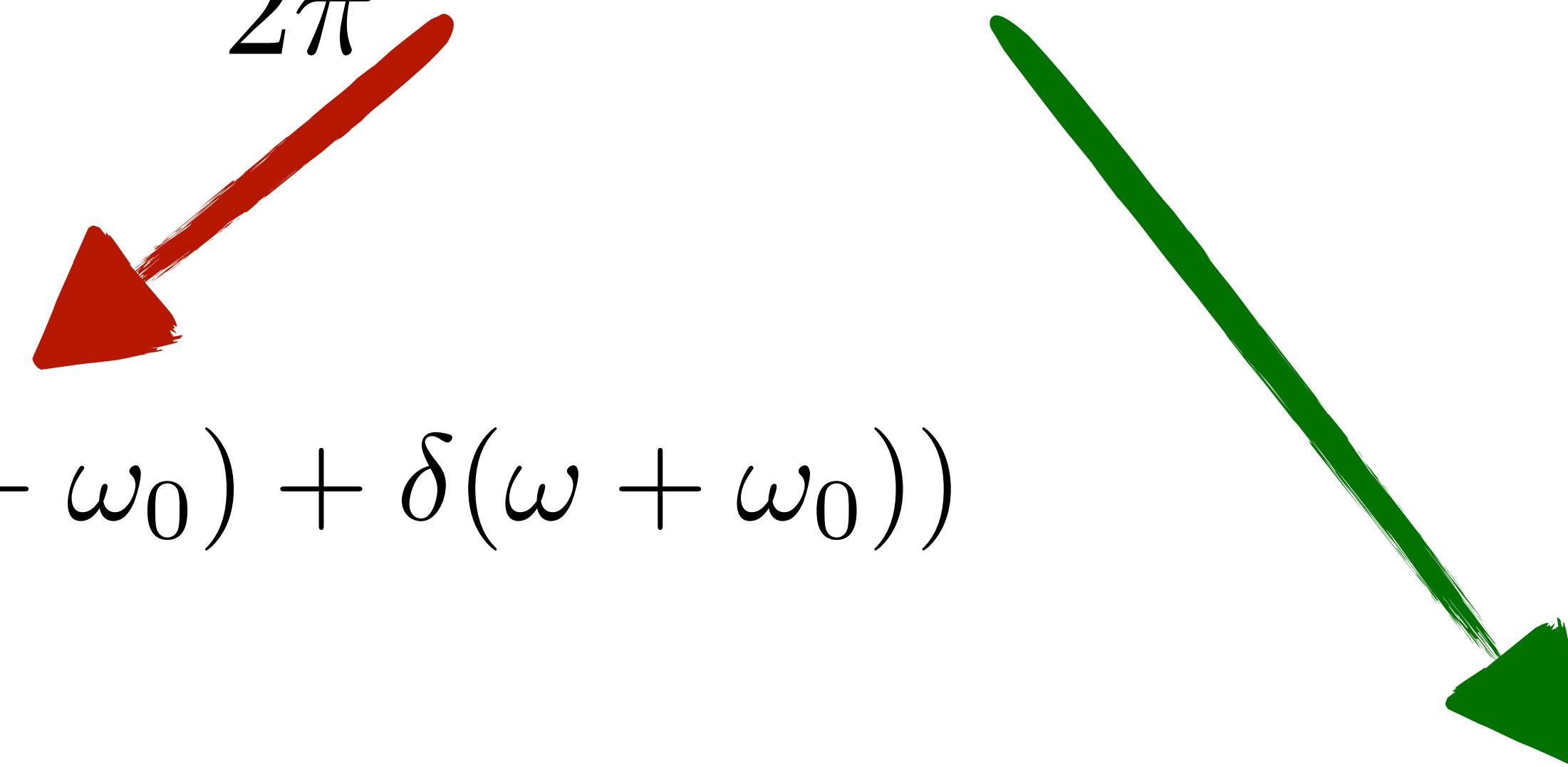

$$x(t) = \cos(\omega_0 t) \text{rect}_L(t)$$

product in time ==> convolution in frequency


$$X(\omega) = \frac{1}{2\pi} Z_G(\omega) * F(\omega)$$

Truncated cosine signal: method 2

$$X(\omega) = \frac{1}{2\pi} Z_G(\omega) * F(\omega)$$



$$Z_G(\omega) = \pi (\delta(\omega - \omega_0) + \delta(\omega + \omega_0))$$

$$F(\omega) = \text{sinc}_{L/2}(\omega) = \frac{2 \sin(\omega \frac{L}{2})}{\omega}$$

Truncated cosine signal: method 2

Using the property of the convolution with deltas:

$$X(\omega) = \frac{1}{2\pi} \pi \operatorname{sinc} \frac{L}{2} (\omega - \omega_0) + \frac{1}{2\pi} \pi \operatorname{sinc} c \frac{L}{2} (\omega + \omega_0)$$

and we obtain again:

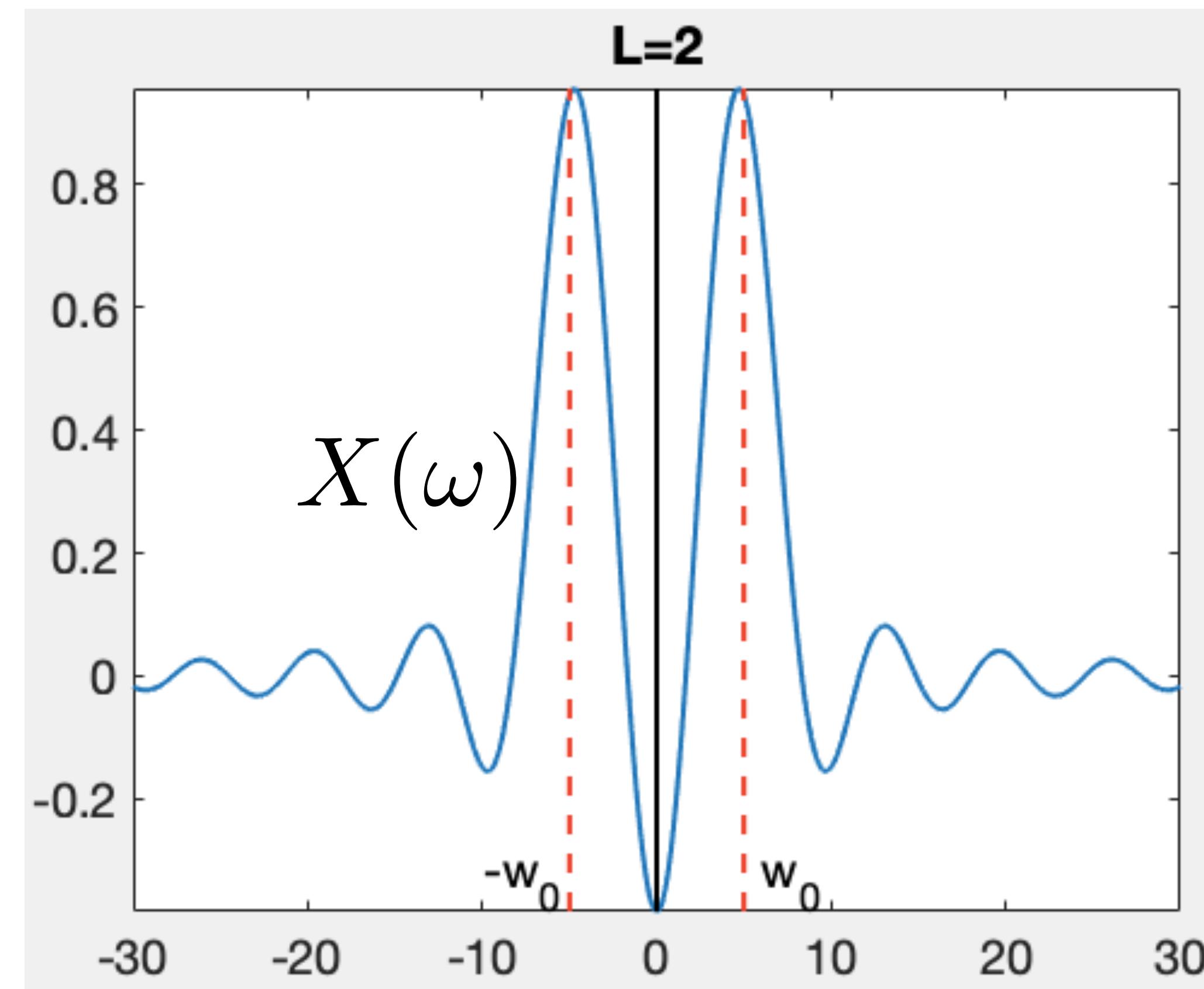
$$X(\omega) = \frac{1}{2} \operatorname{sinc} \frac{L}{2} (\omega - \omega_0) + \frac{1}{2} \operatorname{sinc} \frac{L}{2} (\omega + \omega_0)$$

$$X(\omega) = \frac{\sin((\omega - \omega_0) \frac{L}{2})}{\omega - \omega_0} + \frac{\sin((\omega + \omega_0) \frac{L}{2})}{\omega + \omega_0}$$

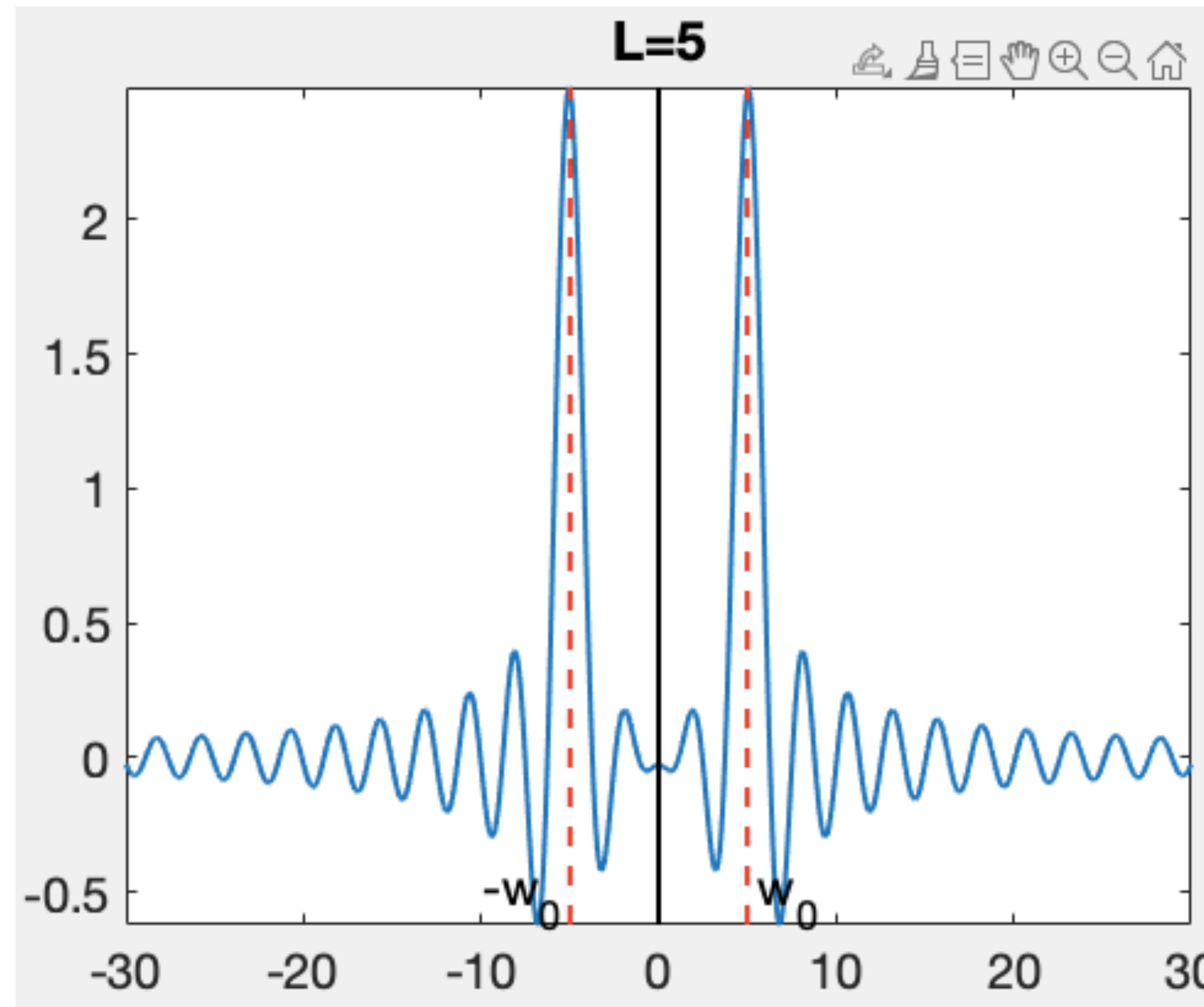
Plotting the Stand. FT of the truncated cosine signal

Plotting $X(w)$

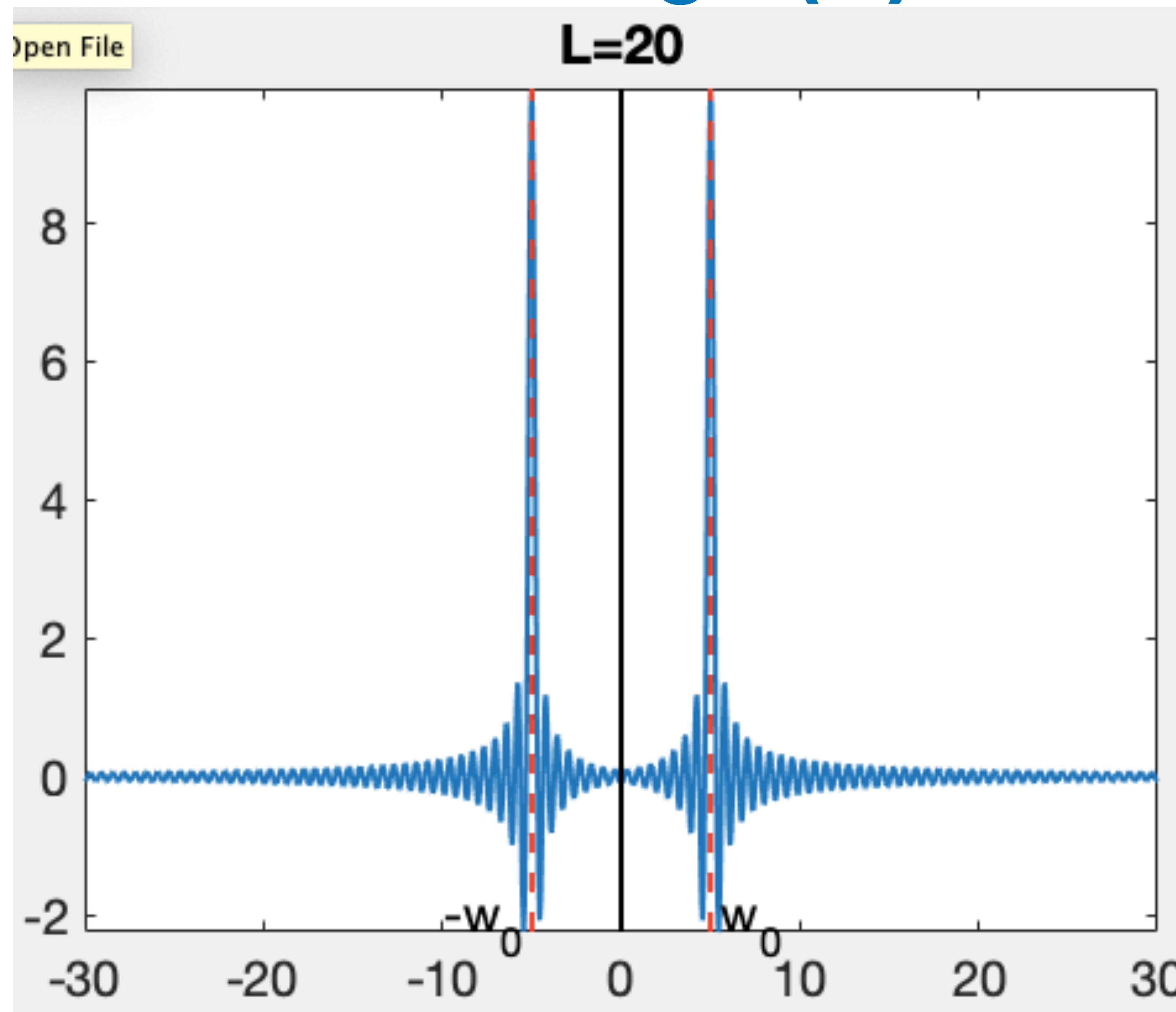
Since $X(w)$ is real in this case, we can plot directly $X(w)$ (without taking the module)



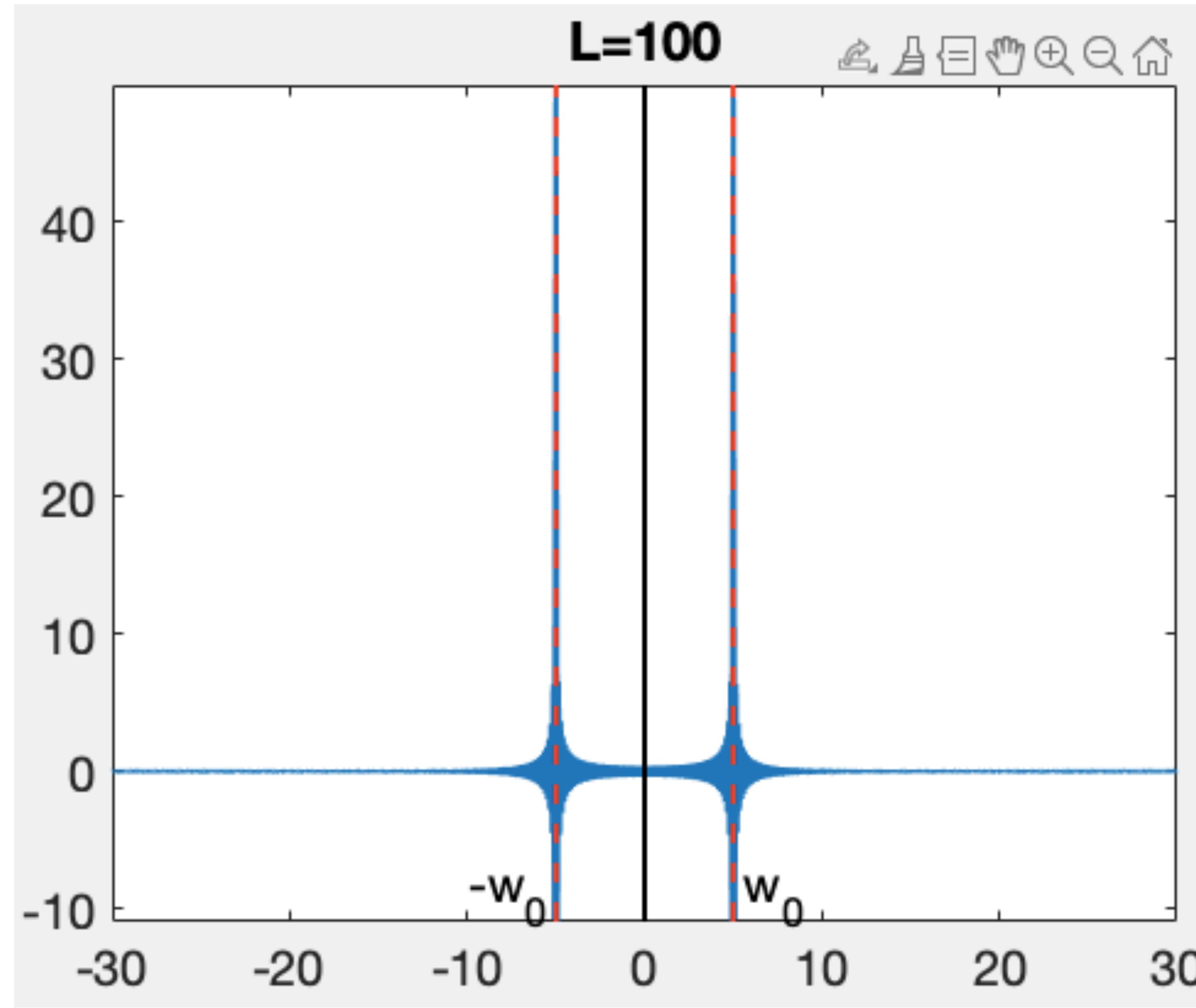
Plotting X(w)



Plotting X(w)

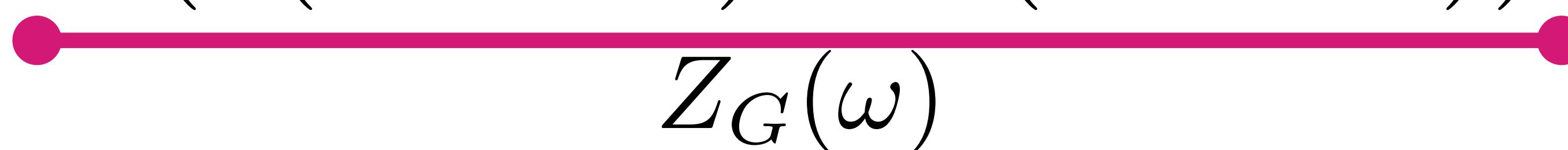


Plotting X(w)



Plotting X(w)

Note that, as L grows to infinity, we have:

$$X(\omega) \longrightarrow \pi (\delta(\omega - \omega_0) + \delta(\omega + \omega_0))$$

$$Z_G(\omega)$$

Since the rectangle $f(t)$ tends to be $f(t)=1$ (a constant signal).

Questions?