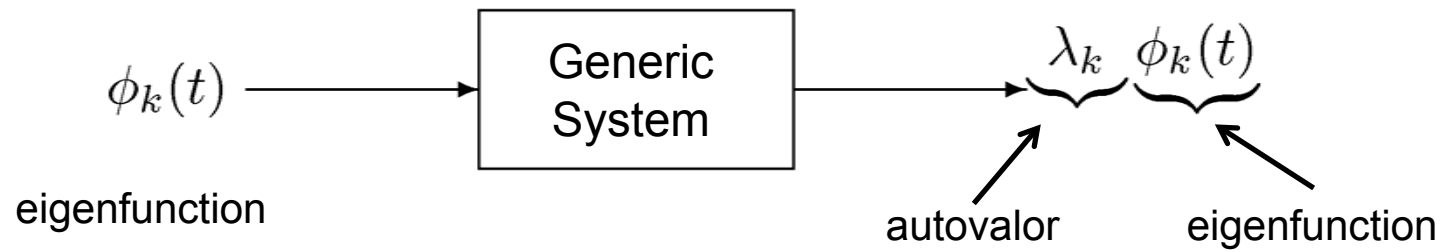
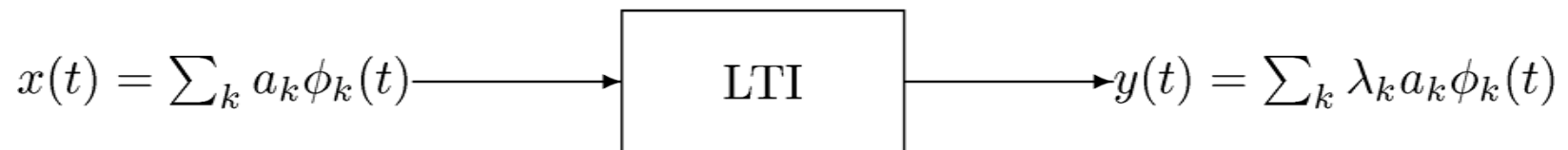


## Eigenfunctions of LTI systems: exponentials

➤ What is an eigenfunction?



- Output with input an eigenfunction → the same eigenfunction multiplied for a scalar number/factor (called eigenvalue)
- For the linearity of LTI systems:



## Exponentials as eigenfunctions of LTI systems

Very important slide....

$$x(t) = e^{st} \longrightarrow \boxed{h(t)} \longrightarrow y(t) \quad s: \text{complex number}$$

$$y(t) = \int_{-\infty}^{\infty} h(\tau) e^{s(t-\tau)} d\tau = \left[ \int_{-\infty}^{\infty} h(\tau) e^{s\tau} d\tau \right] e^{st} = \underbrace{H(s)}_{\text{eigenvalue}} \underbrace{e^{st}}_{\text{eigenfunction}}$$

H(s) is also complex number, in general

$$x(t) \longrightarrow \boxed{h(t)} \longrightarrow y(t) \quad H(s) = \int_{-\infty}^{\infty} h(t) e^{-st} dt$$

Laplace Transform

➤ If x(t) is a combination of exponential complex signals we get :

$$x(t) = \sum_k a_k e^{s_k t} \longrightarrow y(t) = \sum_k \underbrace{H(s_k)}_{\text{eigenvalue}} a_k e^{s_k t}$$

Zeros, poles.... We can understand this study

## Properties of the LTI systems in DT

- The output  $y[n]$  of a LTI system with input a complex exponential, is other complex exponential with the **same frequency** and, generally, different phase and amplitude:

$$x[n] = Ae^{j(\Omega_0 n + \phi)} \rightarrow \boxed{\text{LTI system}} \rightarrow y[n]$$

$$y[n] = A'e^{j(\Omega_0 n + \phi')} = \frac{A'}{A} Ae^{j(\Omega_0 n + \phi)} e^{j(\phi' - \phi)} = \left( \frac{A'}{A} e^{j(\phi' - \phi)} \right) x[n]$$

- The complex exponentials are **eigenfunctions** for the LTI systems.
- The multiplying factor is the corresponding **eigenvalue** (corresponding to frecuencia  $\Omega_0$ )

$$(A_0 e^{j\phi_0}) = \left( \frac{A'}{A} e^{j(\phi' - \phi)} \right)$$

## Properties of the LTI systems in DT

- The output of an LTI systems when the input is a sum of complex exponentials with **different frequencies**, is the sum of the **same** complex exponentials with different **phase** and **amplitude**

$$x[n] = \sum_{k=0}^K e^{j\Omega_k n} \rightarrow \boxed{\text{LTI systems}} \rightarrow y[n] = \sum_{k=0}^K A_k e^{j\phi_k} \cdot e^{j(\Omega_k n)}$$

- Then, the output **y[n]** **NEVER** will be contain a frequency that is not contained in the input **x[n]**.

# Frequency response of LTI systems

## The response of LTI systems to complex exponentials

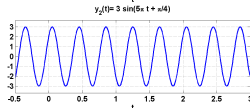
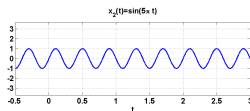
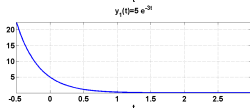
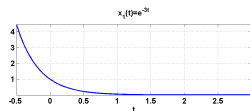
- Consider a continuous time LTI system, characterized by  $h(t)$ .
- Suppose that the LTI system input is a complex exponential  $x(t) = e^{s_0 t}$ , being  $s_0 = \sigma + j\omega$ .
- The LTI system output is calculated by means of the convolution method:

$$\begin{aligned}
 y(t) &= x(t) * h(t) = e^{s_0 t} * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t - \tau)d\tau = \int_{-\infty}^{\infty} x(t - \tau)h(\tau)d\tau = \\
 &= \int_{-\infty}^{\infty} e^{s_0(t-\tau)}h(\tau)d\tau = e^{s_0 t} \int_{-\infty}^{\infty} h(\tau)e^{-s_0 \tau}d\tau = x(t)H(s_0)
 \end{aligned}$$

- $H(s_0)$  is a (complex) constant, that depends on the impulse response and on the exponent of the system input (the exponential function).
- Complex exponential signals are known as *eigenfunctions* of the LTI systems, as the system output to these inputs equals the input multiplied by a constant factor. Both amplitude and phase may change, but the frequency does not change.

# Frequency response of LTI systems

## Response to real exponential functions and to sinusoids



## System function

- If we represent the factor scales for any  $s_0$ , we obtain the system function:

**LAPLACE transform**

$$H(s) = \int_{-\infty}^{\infty} h(\tau) e^{-s\tau} d\tau$$

- Note that this function includes the system response to any complex exponential function.
- Also note that this function depends on the impulse response, that includes all the information related to the LTI system.

# 1. Introducción: autovalores y autofunciones

- Para un sistema LTI con respuesta al impulso  $h[n]$  la respuesta a una exp. compleja es otra exp. compleja:

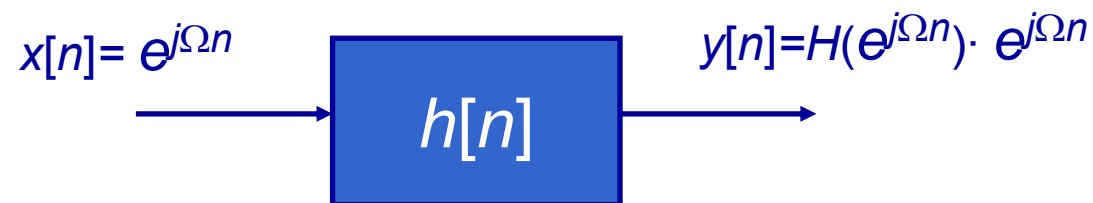
$$x[n] = z_0^n$$

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k] = \sum_{k=-\infty}^{\infty} h[k]z_0^{n-k} = z_0^n \sum_{k=-\infty}^{\infty} h[k]z_0^{-k}$$

$$y[n] = z_0^n H(z_0)$$

- Siendo:

- ★  $z_0^n = |z_0|^n e^{j\Omega_0 n} \equiv$  AUTOFUNCIÓN
- ★  $H(z_0) \equiv$  AUTOVALOR  $\in \mathbb{C}$
- ★ Por ser  $z_0^n$  *autofunción*, también lo es  $e^{j\Omega n}$  ( $z^n$  con  $|z|=1$ )
- ★ Por ser  $H(z_0)$  *autovalor*, también lo es  $H(e^{j\Omega_0 n})$



## 2. Respuesta de sistemas LTI a señales exponenciales complejas

- Supongamos que la entrada es una combinación lineal de exponenciales:

$$x[n] = \sum_{k=1}^N a_k e^{j\Omega_k n} \Rightarrow$$

$$y[n] = h[n] * x[n] = \sum_{k=1}^N a_k h[n] * e^{j\Omega_k n}$$

$$y[n] = \sum_{k=1}^N a_k H(e^{j\Omega_k}) e^{j\Omega_k n} = \sum_{k=1}^N b_k e^{j\Omega_k n}$$

$$H(e^{j\Omega_k}) \equiv H(\Omega_k) \in \mathbb{C}$$
$$a_k, b_k \in \mathbb{C}$$

- La respuesta es otra combinación lineal de las mismas exponenciales.
- Esto es considerablemente más sencillo que realizar la convolución.
- Por ello vamos a estudiar qué tipo de señales se pueden representar mediante combinación lineal de exponenciales complejas.

