

TOPIC 5  
ZETA TRANSFORM  
**PART 1**

# ZETA TRANSFORM

**DEFINITION:**

Region Of Convergence (ROC)

$$x[n] \longleftrightarrow X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n} = \mathcal{Z}\{x[n]\}$$

$z \in \text{ROC}$

This is the so-called “Analysis Equation”:  
in the sense that we go from time domain-  $x[n]$  -  
to the transform domain -  $X(z)$ .

$$z \in \mathbb{C}$$

$$X(z) \in \mathbb{C}$$

It is a generalization/extension of the Fourier Transform for a signal in discrete time (DTFT).

# ZETA TRANSFORM

$$X(z) = \sum_{n=-\infty}^{+\infty} x[n]z^{-n}$$

Region of Convergence

$z \in \text{ROC}$

$$z = r e^{j\Omega}$$

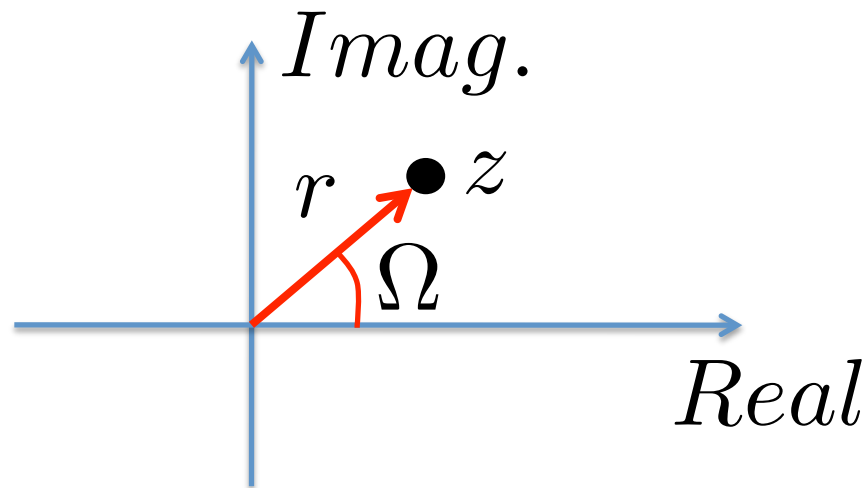
We will use the polar representation for the variable  $z$ .

FREQUENCY

# POLAR REPRESENTATION

$$z = r e^{j\Omega}$$

- For each  $r$  and  $\Omega$  we have a complex number  $z$  (a point in the complex plane).



# RELATIONSHIP with other topics/fields

- Zeta transform coincides with the so-called **Laurent Series - Laurent expansion** (in complex analysis).
- The inverse Zeta transform is related to the so-called **Cauchy integral formula** and residue theorem (in complex analysis).

# RELATIONSHIP with other topics/fields

➤ Since the Laurent Series generalizes the Taylor series, the Zeta transform is a generalization of the Taylor series; Indeed, consider only the negative values of  $n$ , we have

$$X(z) = \sum_{n=-\infty}^0 x[n]z^{-n} = \sum_{k=0}^{\infty} x[k]z^k$$

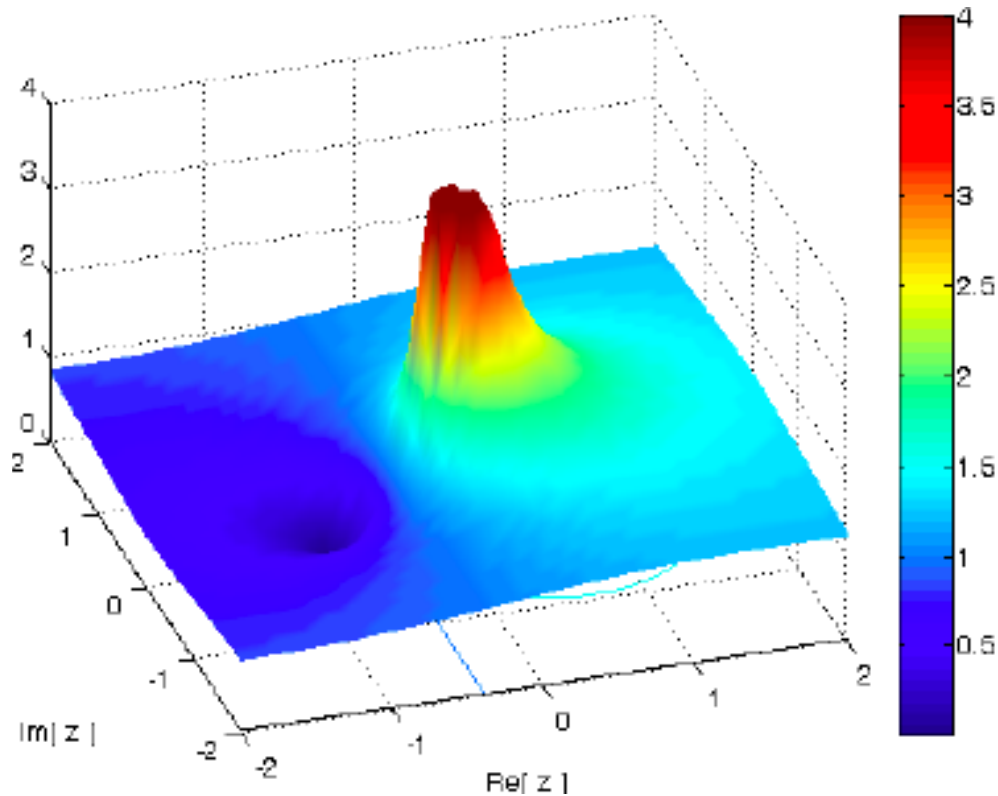
↑  
k=-n

# RELATIONSHIP with other topics/fields

- Zeta transform is related to the solution of the **difference equations**.
- as a consequence, it is related also to digital filtering theory (ARMA, AR, MA, IIR, FIR etc.).

# Graphical example of $|X(z)|$

- The Zeta transform is defined in the complex domain (except some points or regions where there is not convergence; later we will talk about that); it takes complex values then we plot the module (for instance).





# Inverse Zeta Transform

- Almost never used in practice.
- Synthesis equation.

$$x[n] = \frac{1}{2\pi j} \oint X(z) z^{n-1} dz$$

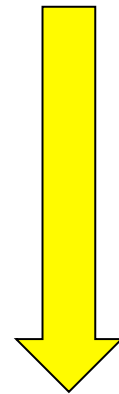
LINE INTEGRAL – CURVE INTEGRAL (in a “close”  
“circular” curve)

# Recovering the FOURIER TRANSFORM

$$\begin{aligned} X(z) &= \sum_{n=-\infty}^{+\infty} x[n] z^{-n} \\ &= \sum_{n=-\infty}^{+\infty} x[n] (r e^{j\Omega})^{-n} \\ &= \sum_{n=-\infty}^{+\infty} x[n] r^{-n} e^{-j\Omega n} \end{aligned}$$

# Recovering the FOURIER TRANSFORM

$$X(re^{j\Omega}) = X(r, \Omega) = \sum_{n=-\infty}^{+\infty} x[n]r^{-n}e^{-j\Omega n}$$

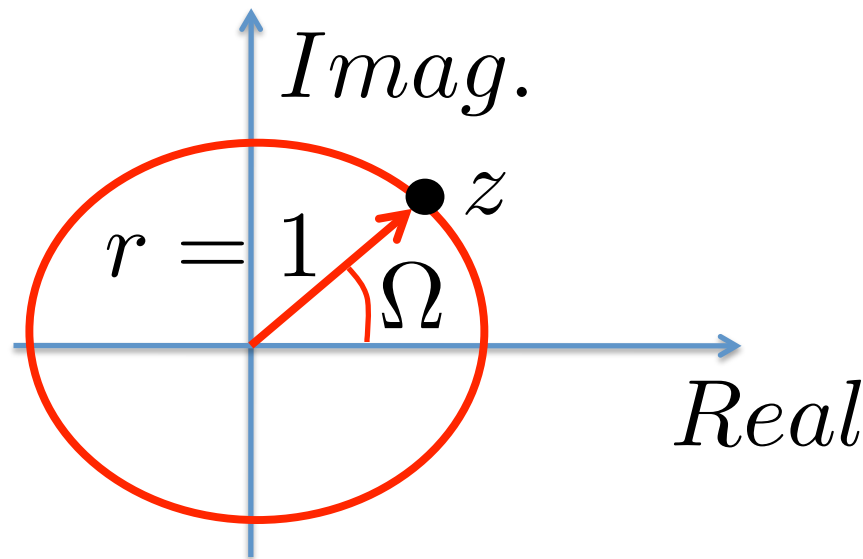


$$r = 1$$

$$X(e^{j\Omega}) = X(1, \Omega) = X(\Omega) = \sum_{n=-\infty}^{+\infty} x[n]e^{-j\Omega n}$$

# Recovering the FOURIER TRANSFORM

$$X(e^{j\Omega}) = X(1, \Omega) = X(\Omega) = \sum_{n=-\infty}^{+\infty} x[n]e^{-j\Omega n}$$



- The Fourier Transform is defined in this "circle"
- The ROC must contain this circle in order to have the FT !

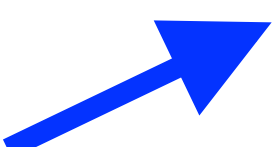
# Why ZETA TRANSFORM?

$$z = r e^{j\Omega}$$

- The variable  $r$  can help the convergence of the series (for some signals  $x[n]$ ).
- **RECALL** For each  $r$  and  $\Omega$  we have a complex number  $z$  (a point in the complex plane).

# EXAMPLE

$$x[n] = a^n u[n]$$

$$\begin{aligned} X(z) &= \sum_{n=-\infty}^{\infty} a^n u[n] z^{-n} \\ &= \sum_{n=0}^{\infty} (az^{-1})^n \\ &= \frac{1}{1 - az^{-1}} = \frac{z}{z - a} \end{aligned}$$


If  $|az^{-1}| < 1$ , i.e.,  $|z| > |a|$

**ROC !!!!!**  
Region of convergence



# Region of convergence (ROC)

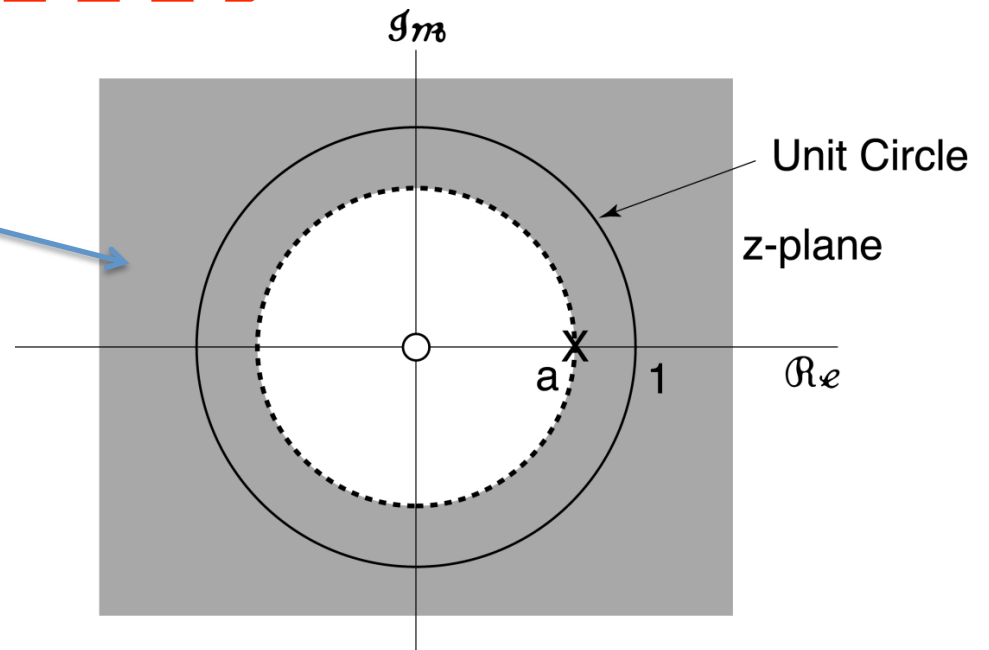
$$x[n] = a^n u[n] \longrightarrow X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

If  $|az^{-1}| < 1$ , i.e.,  $|z| > |a|$

ROC !!!!!

Region of convergence

The ROC is depicted in "grey"

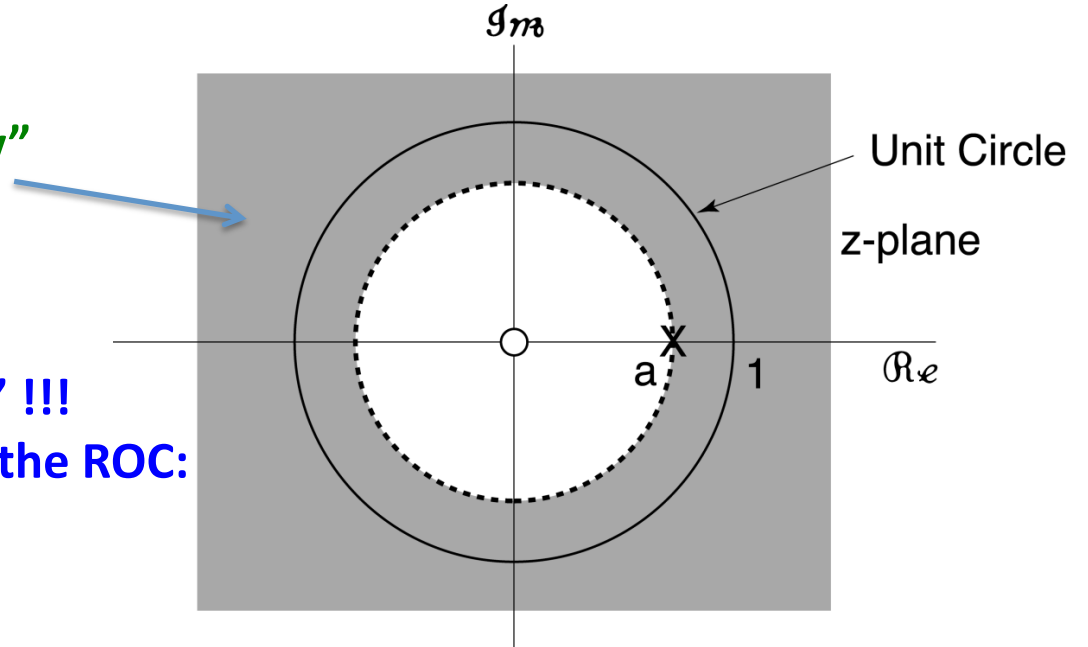


# Region of convergence (ROC)

ROC = {all  $z \in \mathbb{C}$  such that  $X(z)$  exists (finite)}

ROC = {all  $z \in \mathbb{C}$  such that  $\sum_{n=-\infty}^{+\infty} x[n]z^{-n}$  converges }

The ROC is depicted in "grey"



Does the FT exist? In this case "yes" !!!  
Since the unit circle is contained in the ROC:  
if  $a < 1$ , then the FT exists;  
if  $a > 1$ , then the FT does not exist !



# Region of convergence (ROC)

$$x[n] = a^n u[n] \longrightarrow X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

**We have always  
to obtain/provide:  
X(z) jointly with the ROC.**

$$\text{ROC} = \left\{ |z| > |a| \right\}$$

ROC: Region Of Convergence

# Region of convergence (ROC)

The ROC is an essential part of the information.

# Other example

$$x[n] = -a^n u[-n - 1]$$

---

$$X(z) = \sum_{n=-\infty}^{\infty} \{-a^n u[-n - 1] z^{-n}\}$$

$$= - \sum_{n=-\infty}^{-1} a^n z^{-n} = - \sum_{n=1}^{\infty} a^{-n} z^n = 1 - \sum_{n=0}^{\infty} (a^{-1} z)^n$$

$$= 1 - \frac{1}{1 - a^{-1} z} = \frac{a^{-1} z}{a^{-1} z - 1}$$

$$= \frac{z}{z - a}$$

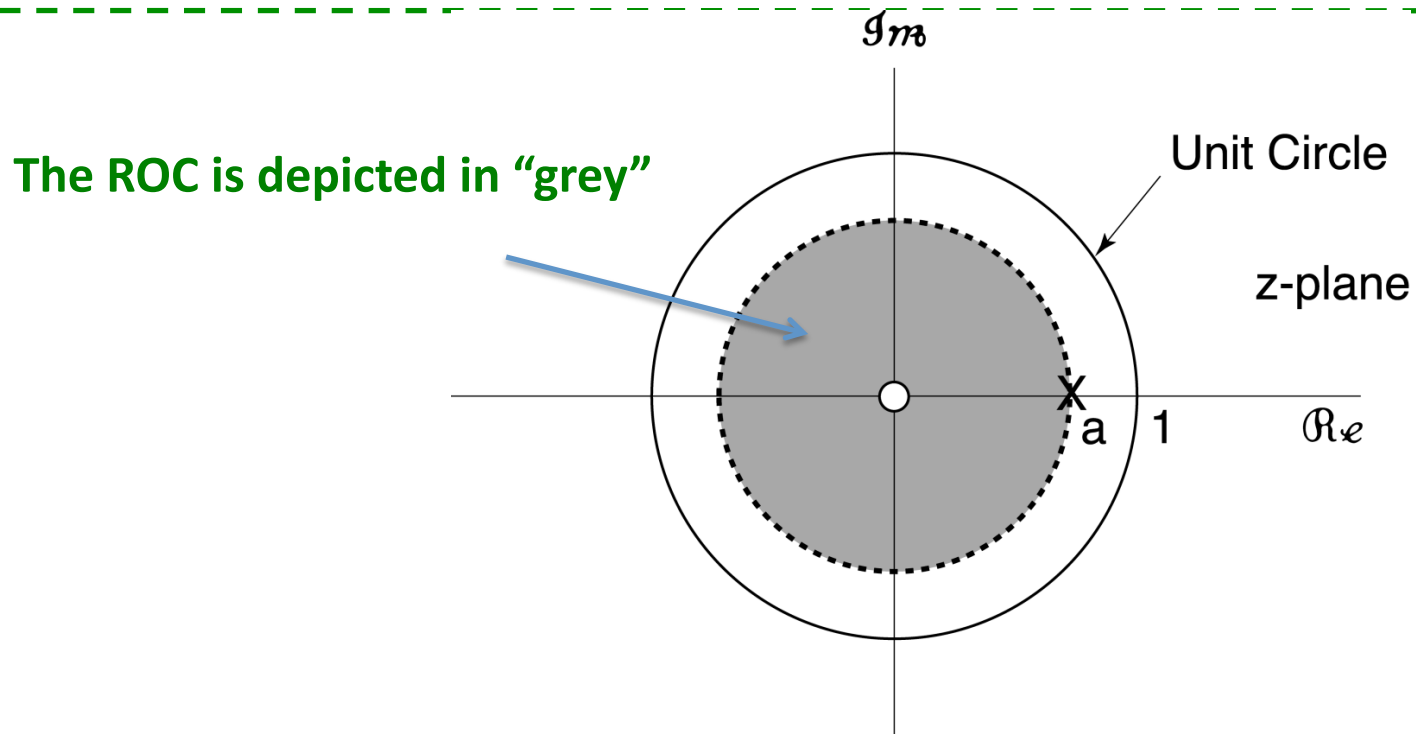
ROC: Region Of Convergence

If  $|a^{-1} z| < 1$ , i.e.,  $|z| < |a|$

**IT IS THE SAME X(z)  
of the other  
example!!**

# Other example

$$x[n] = -a^n u[-n - 1] \longrightarrow X(z) = \frac{z}{z - a} \quad \text{ROC } |z| < |a|$$



If  $a < 1$  then the FT does not exist....

If  $a > 1$  then the FT will exist....

(In the figure above  $a < 1$ , the FT does not exist)

# About ROCs of the Zeta transform

The ROCs are always “circular pieces/ portions” of the complex plane, possibly infinite pieces (as we saw in the previous slides; it can be also like a “donut”, we will see this case).

# SUMMARY of the examples

$$x[n] = a^n u[n]$$



$$X(z) = \frac{z}{z - a}$$

ROC

$$|z| > |a|$$



$$x[n] = -a^n u[-n - 1]$$



$$X(z) = \frac{z}{z - a}$$

ROC

$$|z| < |a|$$

**THE SAME ZETA TRANSFORM BUT DIFFERENT ROCs !!!!**

...Then, the ZETA TRANSFORM IS:

$$X(z) + \text{ROC}$$

**Given a signal in time  $x[n]$ ...**

$$x[n] \longrightarrow X(z) + \text{ROC}$$

**To a signal  $x[n]$  in time corresponds one  $X(z)$  and one ROC associated. The pair  $X(z)$ +ROC is associated to  $x[n]$ .**

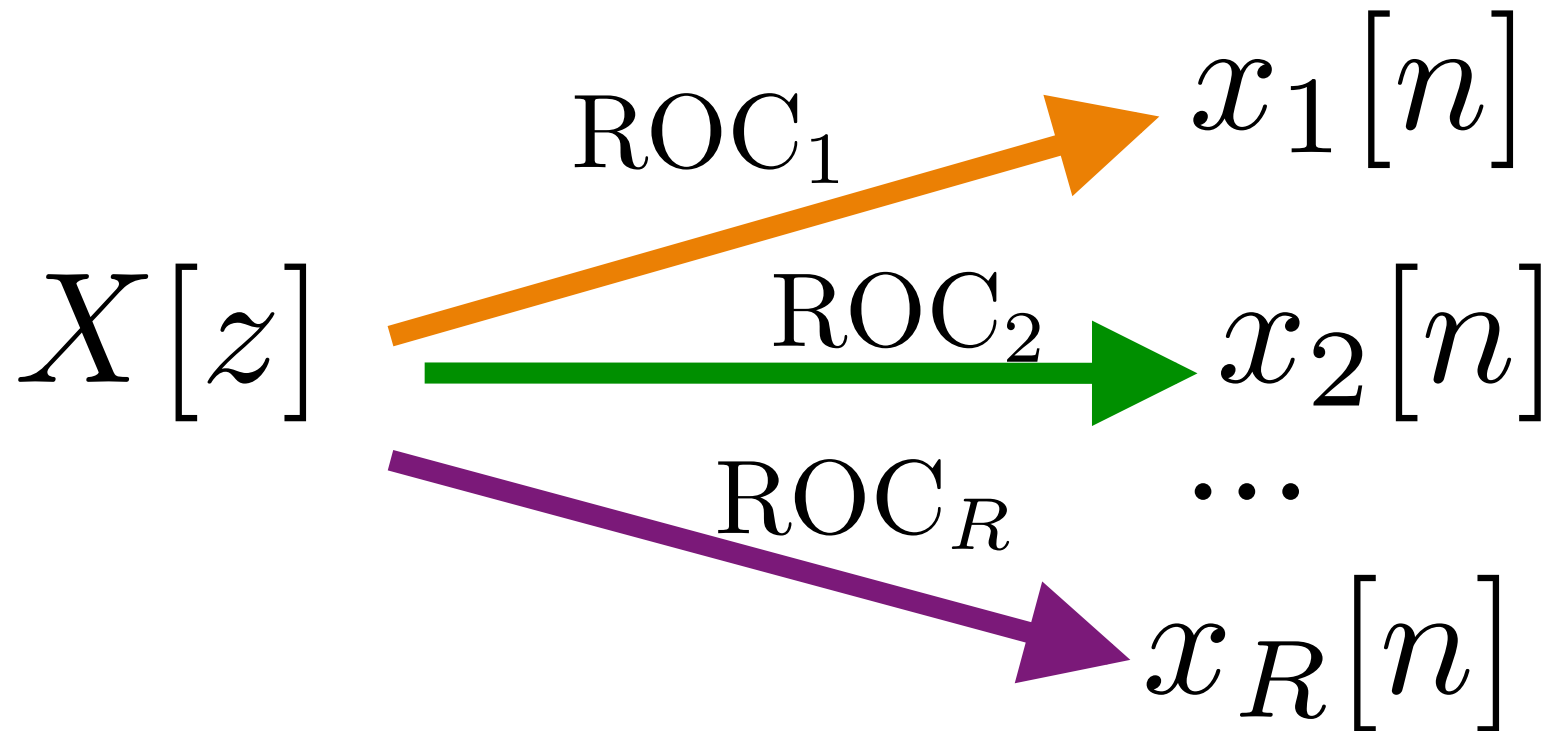


**Given  $X[z]$ +ROC ...**

$$X(z) + \text{ROC} \longrightarrow x[n]$$

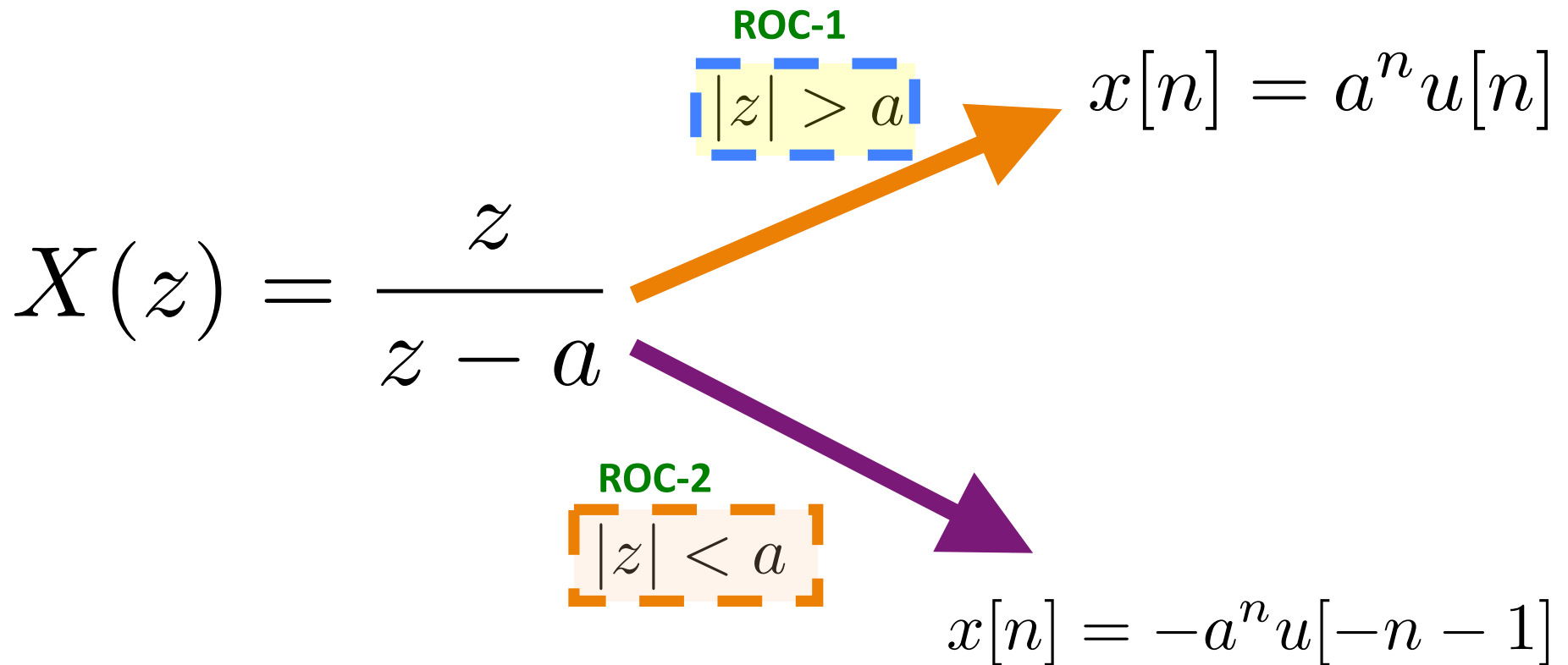
**Given a pair  $X[z]$ +ROC, in time we a  
UNIQUE (only one) signal  $x[n]$ ,  
corresponding to this pair ( $X[z]$ +ROC).**

# Given just $X[z]$ ...



Given only  $X[z]$ , we can have different signals in time (which provide the same  $X[z]$ ). Each signal corresponds to a specific ROC.

# Given just $X[z]$ : example



# Poles and zeros

POLES: all values of  $z$  such that  $X(z) \rightarrow \infty$

ZEROS: all values of  $z$  such that  $X(z) = 0$

# Poles and zeros: example


$$X(z) = \frac{z}{z - a}$$

One zero at  $z=0$

One pole at  $z=a$

# Poles and zeros: other example

$$X(z) = z^2 - 4$$

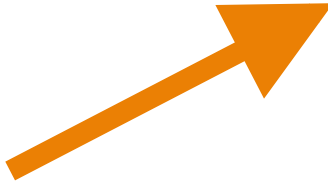


Two zeros at  $z=-2$   
And  $z=2$

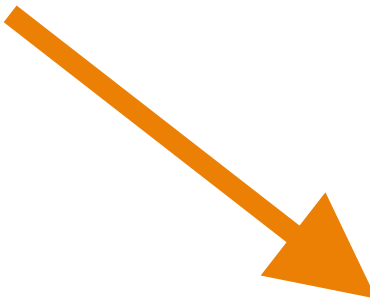
ONE pole at  
 $z=\text{Infinity}$   
("almost" no  
poles... )

# Poles and zeros: other example

$$X(z) = z^2 + 4$$



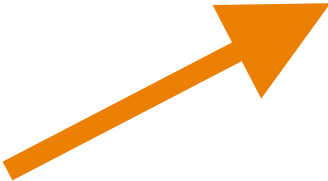
Two zeros at  $z=-2j$   
and  $z=2j$



ONE pole at  
 $z=\text{Infinity}$   
("almost" no  
poles... )

# Poles and zeros: other example

$$X(z) = \frac{z - 1}{z^2 + 4}$$



**One zero at  $z=1$   
And one zero at  
 $z=\text{Infinity}$**



**Two poles at  $z=-2j$   
and  $z=2j$**



# ROCs and poles

VERY IMPORTANT SLIDE !!

**A ROC does not contain poles (never!)**

**Generally, the poles are in the boundaries of the ROCs. If  $X(z)$  is rational (a fraction of polynomials) this is always the case.**

# ROCs and poles

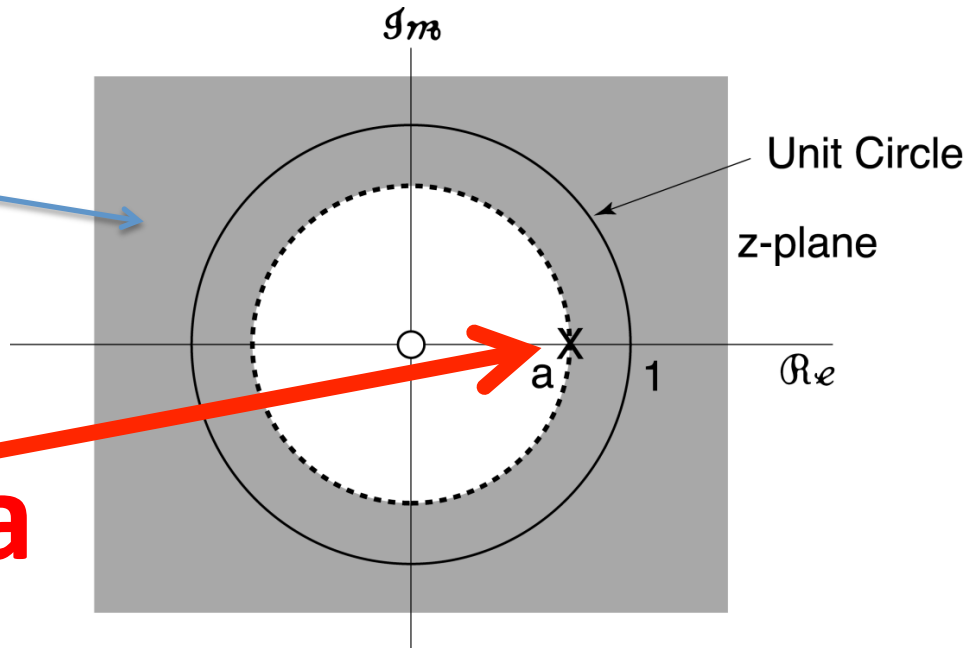
Namely, in the case of  $X(z)$  is rational  
(a fraction of polynomials) the poles  
“define/determine” the ROC.

# ROCs and poles: examples

$$x[n] = a^n u[n] \longrightarrow X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

If  $|az^{-1}| < 1$ , i.e.,  $|z| > |a|$

The ROC is depicted in "grey"



**POLE at z=a**

# ROCs and poles: examples

$$x[n] = -a^n u[-n - 1] \longrightarrow X(z) = \frac{z}{z - a} \quad \text{ROC } |z| < |a|$$

