

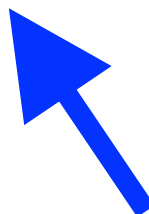
TOPIC 5  
ZETA TRANSFORM

**PART 5**

**“back in time domain”**

# Inverse Zeta Transform

- Almost never used in practice.
- Synthesis equation.

$$x[n] = \frac{1}{2\pi j} \oint X(z) z^{n-1} dz$$


LINE INTEGRAL – CURVE INTEGRAL (in a “close”  
“circular” curve)

ALTERNATIVES ? →

**PARTIAL FRACTION DECOMPOSITION  
(DECOMPOSITION FOR “SIMPLE  
FRACTIONS” or  
PARTIAL FRACTION EXPANSION)**

**We will see JUST FEW special cases...**

**..even without part-fraction decomposition...**

$$X(z) = z^5 + 2z - 1$$

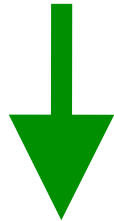


$$x[n] = \delta[n + 5] + 2\delta[n + 1] - \delta[n]$$

**ROC: all the complex plane,  
except Infinity....**

**...other very simple case...**

$$X(z) = \frac{z^5 + 2z - 1}{z^3} = z^2 + 2z^{-2} - z^{-3}$$



$$x[n] = \delta[n + 2] + 2\delta[n - 2] - \delta[n - 3]$$

**ROC: all the complex plane,  
except zero and Infinity....  
(are multiple poles? Yes !)**

# PARTIAL FRACTION DECOMPOSITION

**We ONLY consider the case where:**

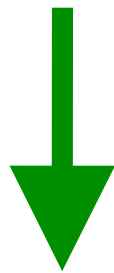
- **Degree Numerator  $\leq$  Degree Denominator**
- **The poles are all real and different**
- **The poles are “simple” (degree 1)**

# PARTIAL FRACTION DECOMPOSITION

$$\frac{P(x)}{Q(x)}$$

$$Q(x) = (x - \alpha_1)(x - \alpha_2) \cdots (x - \alpha_n)$$

$$\deg P < n,$$



$$\frac{P(x)}{Q(x)} = \frac{c_1}{x - \alpha_1} + \frac{c_2}{x - \alpha_2} + \cdots + \frac{c_n}{x - \alpha_n}$$

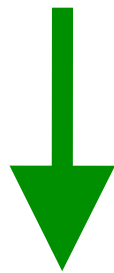
**How to find the constant  $c_i$ ? →**

# PARTIAL FRACTION DECOMPOSITION

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$$Q(x) = (x - \alpha_1)(x - \alpha_2) \cdots (x - \alpha_n)$$

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**How to find the constant  $c_i$ ? →**



# Come back to Example 14

$$X(z) = \frac{3z^2 - \frac{5}{6}z}{(z - \frac{1}{4})(z - \frac{1}{3})} = \frac{3 - \frac{5}{6}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})} = \frac{A}{1 - \frac{1}{4}z^{-1}} + \frac{B}{1 - \frac{1}{3}z^{-1}}$$

**How can we obtain the constant A , B?**

$$X(z) = \frac{A(1 - \frac{1}{3}z^{-1}) + B(1 - \frac{1}{4}z^{-1})}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})}$$

# Come back to Example 14

$$X(z) = \frac{A(1 - \frac{1}{3}z^{-1}) + B(1 - \frac{1}{4}z^{-1})}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})}$$

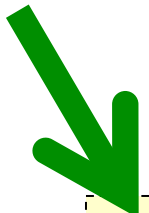
$$X(z) = \frac{A - A\frac{1}{3}z^{-1} + B - B\frac{1}{4}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})}$$

$$X(z) = \frac{A + B + (-A\frac{1}{3} - B\frac{1}{4})z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})}$$

# Come back to Example 14

$$X(z) = \frac{A + B + \left(-A\frac{1}{3} - B\frac{1}{4}\right)z^{-1}}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{1}{3}z^{-1}\right)}$$

We desire that  $= \frac{3 - \frac{5}{6}z^{-1}}{\left(1 - \frac{1}{4}z^{-1}\right)\left(1 - \frac{1}{3}z^{-1}\right)}$


$$\begin{cases} A + B = 3 \\ -\frac{A}{3} - \frac{B}{4} = -\frac{5}{6} \end{cases}$$

# Come back to Example 14

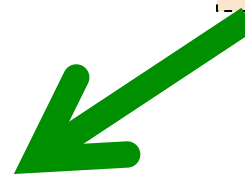
$$\begin{cases} A + B = 3 \\ -\frac{A}{3} - \frac{B}{4} = -\frac{5}{6} \end{cases}$$



$$\begin{aligned} A &= 1 \\ B &= 2 \end{aligned}$$

## Example 14 - problem

$$X(z) = \frac{3z^2 - \frac{5}{6}z}{(z - \frac{1}{4})(z - \frac{1}{3})} = \frac{3 - \frac{5}{6}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})} = \frac{A}{1 - \frac{1}{4}z^{-1}} + \frac{B}{1 - \frac{1}{3}z^{-1}}$$



We obtain the values:  $A = 1$ ,  $B = 2$

$$X(z) = \frac{1}{1 - \frac{1}{4}z^{-1}} + \frac{2}{1 - \frac{1}{3}z^{-1}}$$

$$\updownarrow$$
$$\updownarrow$$
$$\updownarrow$$

$$x[n] = x_1[n] + x_2[n]$$

## Example 14 - problem

$$X(z) = \frac{1}{1 - \frac{1}{4}z^{-1}} + \frac{2}{1 - \frac{1}{3}z^{-1}}$$

$\updownarrow$                        $\updownarrow$                        $\updownarrow$

$$x[n] = x_1[n] + x_2[n]$$

**We are able to invert these ZT (depending on the ROC !!! ) since we have already seen in the first two examples of ZT we did....**

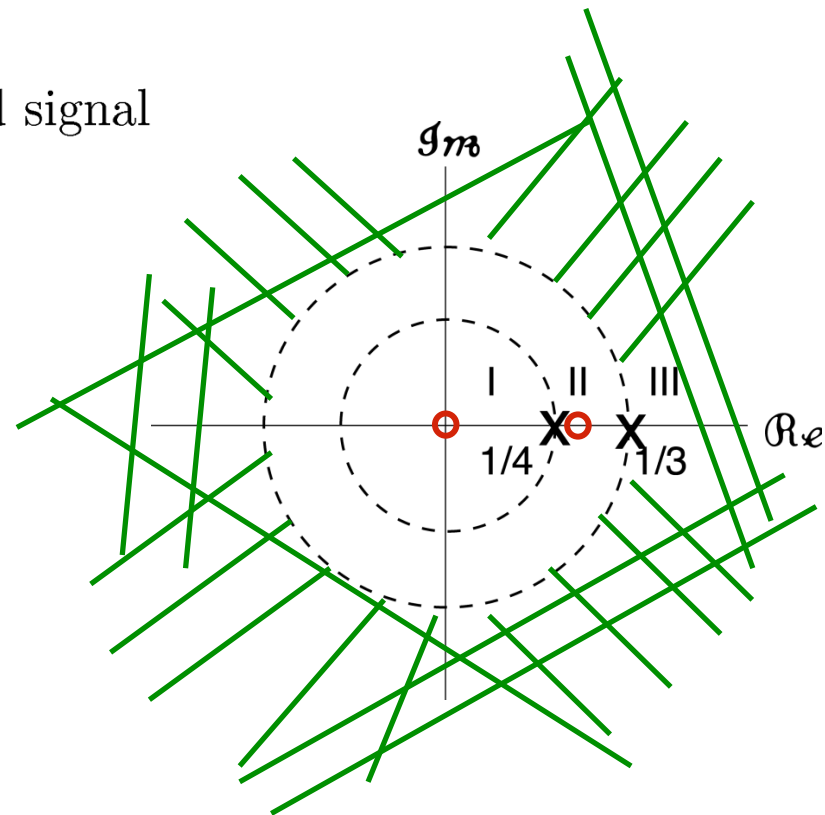
# Example 14 - problem

**3 POSSIBLE SIGNALS IN TIME !!! 3 POSSIBLE SOLUTIONS**

ROC III:  $|z| > \frac{1}{3}$  - right-sided signal

$$x_1[n] = \left(\frac{1}{4}\right)^n u[n]$$

$$x_2[n] = 2 \cdot \left(\frac{1}{3}\right)^n u[n]$$



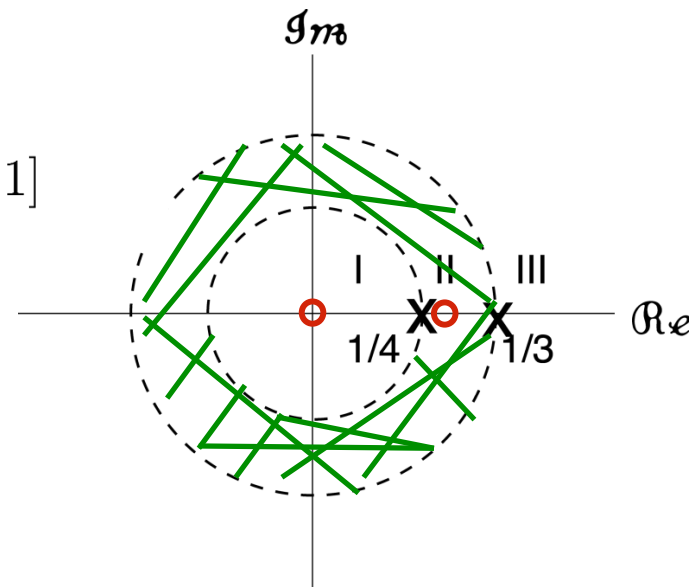
# Example 14 - problem

**3 POSSIBLE SIGNALS IN TIME !!! 3 POSSIBLE SOLUTIONS**

ROC II:  $\frac{1}{4} < |z| < \frac{1}{3}$  - two-sided signal

$$x_1[n] = \left(\frac{1}{4}\right)^n u[n]$$

$$x_2[n] = -2 \cdot \left(\frac{1}{3}\right)^n u[-n-1]$$





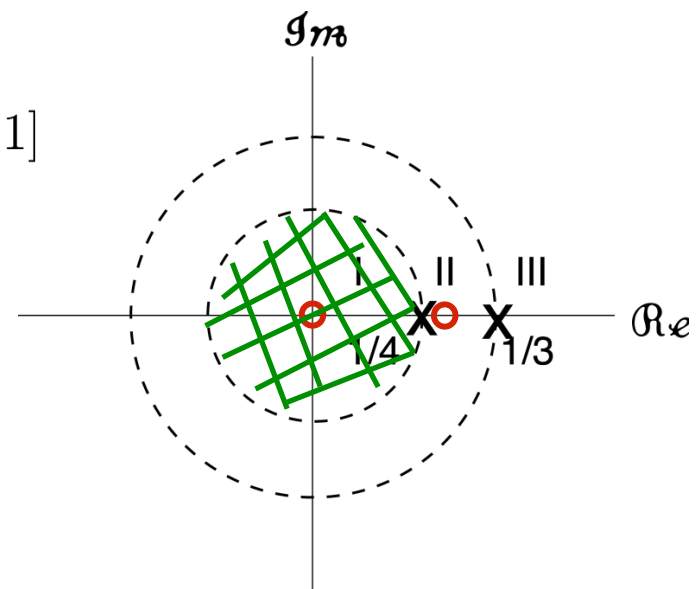
# Example 14 - problem

**3 POSSIBLE SIGNALS IN TIME !!! 3 POSSIBLE SOLUTIONS**

ROC I:  $|z| < \frac{1}{4}$  - left-sided signal

$$x_1[n] = -\left(\frac{1}{4}\right)^n u[-n-1]$$

$$x_2[n] = -2 \cdot \left(\frac{1}{3}\right)^n u[-n-1]$$



## Example 14.5

Considering AGAIN the following ZT :

$$X(z) = \frac{3z^2 - \frac{5}{6}z}{(z - \frac{1}{4})(z - \frac{1}{3})} = \frac{3 - \frac{5}{6}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})} = \frac{A}{1 - \frac{1}{4}z^{-1}} + \frac{B}{1 - \frac{1}{3}z^{-1}}$$

But in this case we assume the ROC:

$$|z| > \frac{1}{3}$$

How many possible signal  $x[n]$  we can have?

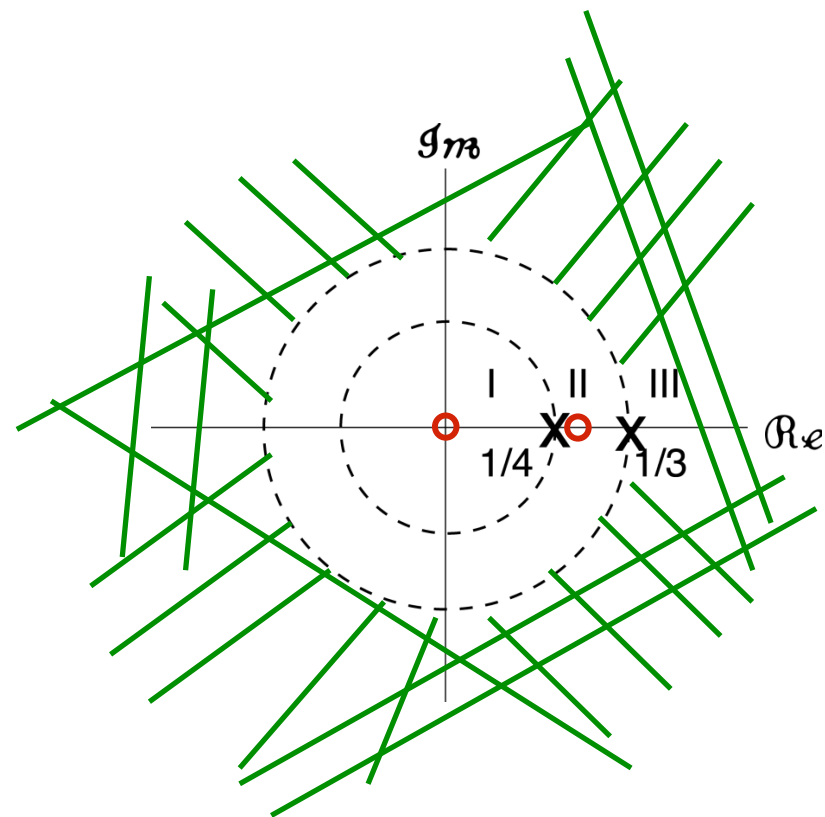
# Example 14.5

**ONLY ONE POSSIBLE SOLUTION !!!**

$|z| > \frac{1}{3}$  - right-sided signal

$$x_1[n] = \left(\frac{1}{4}\right)^n u[n]$$

$$x_2[n] = 2 \cdot \left(\frac{1}{3}\right)^n u[n]$$



## Example 14.6

Considering the signal in the time domain:

$$x[n] = \left(\frac{1}{4}\right)^n u[n] + 2 \left(\frac{1}{3}\right)^n u[n]$$

How many possible Zeta Transforms we can have?

## Example 14.6

ONLY ONE !!!

$$X(z) = \frac{3z^2 - \frac{5}{6}z}{(z - \frac{1}{4})(z - \frac{1}{3})} = \frac{3 - \frac{5}{6}z^{-1}}{(1 - \frac{1}{4}z^{-1})(1 - \frac{1}{3}z^{-1})}$$

With ROC:

$$|z| > \frac{1}{3}$$